



Estimation and Tracking: Principles, Techniques, and Software (Artech House Radar Library)

Yaakov Bar-Shalom, Xiao-Rong Li

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This text is designed for applied researchers and design engineers in civil and military systems. It should also be suitable for graduate students in control systems, aerospace systems and robotics. The book provides engineering tools necessary for the design and evaluation of state estimators in stochastic systems, with guidelines for the selection of estimator design parameters. It includes DynaEst 2.0, an interactive design tool for Kalman filters and an adaptive multiple model estimator.

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